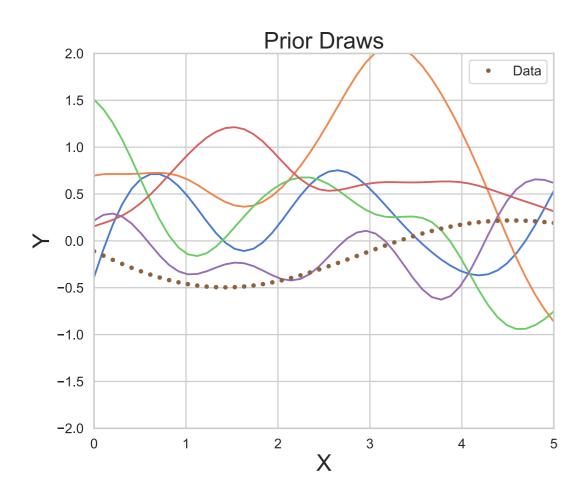
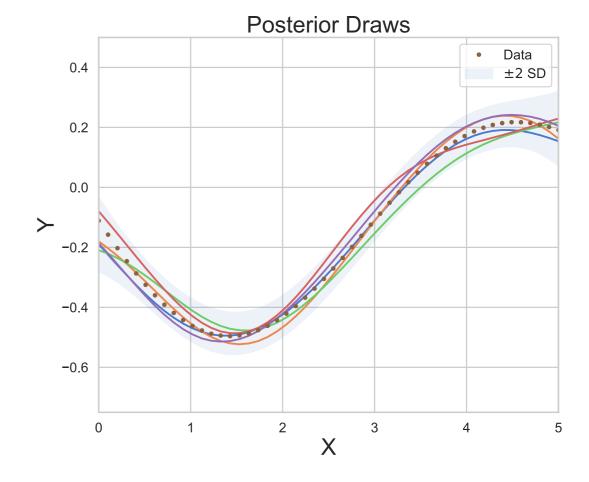


HIGH LEVEL IDEA

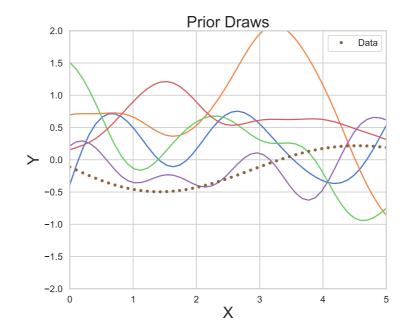
- Gaussian Process (GP): stochastic process for which any finite collection of points is jointly normal
- k(x, x') a kernel function describing covariance

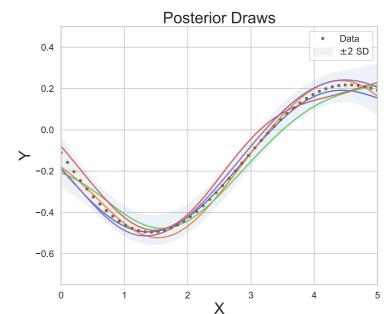
$$y(x) \sim GP(\mu(x), k(x, x'))$$



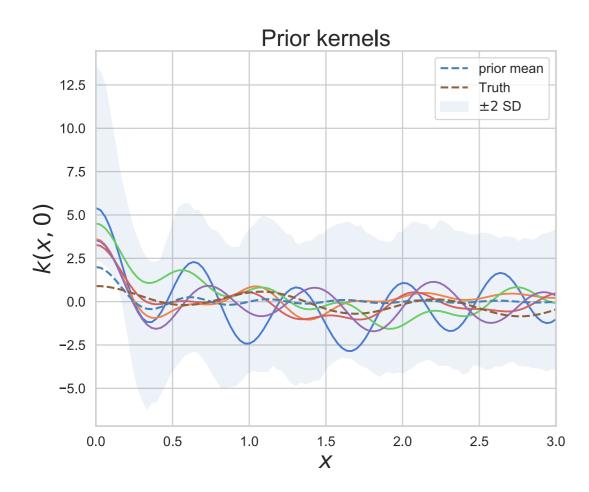


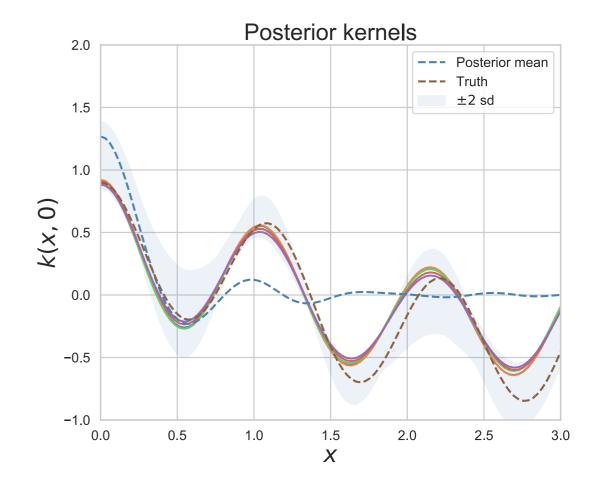
HIGH LEVEL IDEA





 $y(x) \sim GP(\mu(x), k(x, x'))$





- Introduction
 - Mathematical Foundation
 - Model Specification
 - Inference Procedure

- Introduction
- Experimental Results
 - Recovery of known kernels
 - Interpolation and extrapolation of real data

- Introduction
- Experimental Results
- Extension to multi-task time-series
 - Precipitation data

BOCHNER'S THEOREM

If $k(x, x') = k(\tau)$ then we can represent $k(\tau)$ via its spectral density:

$$k(\tau) = \int_{\mathbb{R}} e^{2\pi i \omega \tau} S(\omega) d\omega$$

Learning the spectral representation of $k(\tau)$ is sufficient to learn the entire kernel

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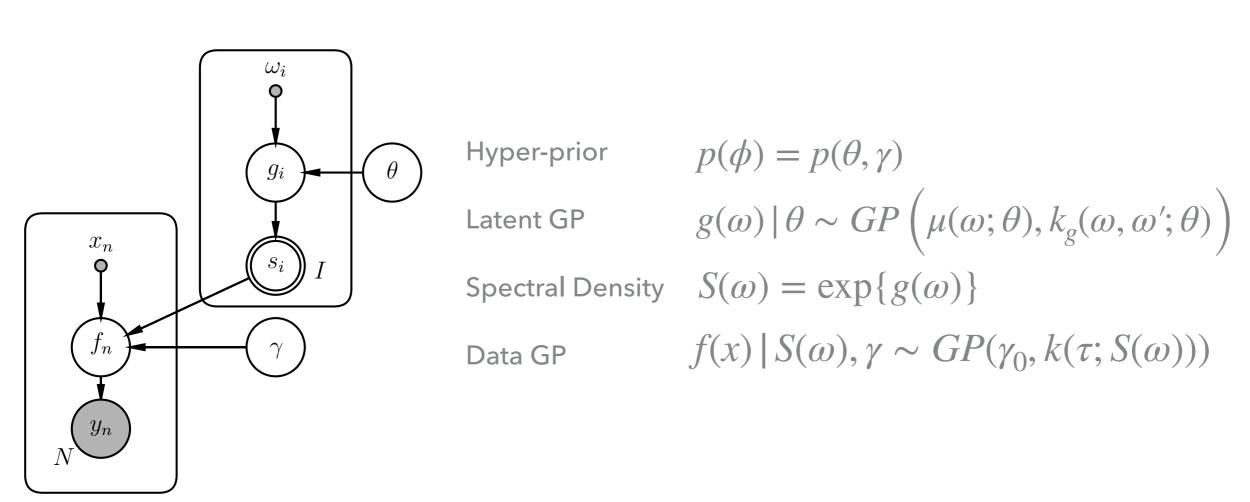
$$k(\tau) = \int_{\mathbb{R}} e^{2\pi i \omega \tau} S(\omega) d\omega$$

- Learning the spectral representation of $k(\tau)$ is sufficient to learn the entire kernel
- Assuming $k(\tau)$ is symmetric and data are finitely sampled, the reconstruction simplifies to:

$$k(\tau) = \int_{[0,\pi/\Delta)} \cos(2\pi\tau\omega) S(\omega) d\omega$$

FUNCTIONAL KERNEL LEARNING

Graphical Model



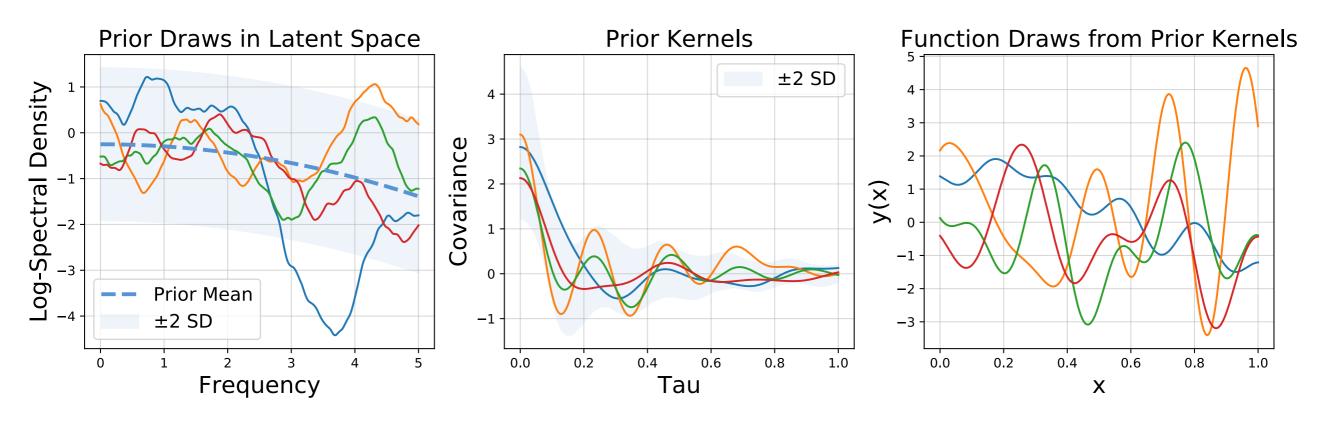
FUNCTIONAL KERNEL LEARNING

Hyper-prior $p(\phi) = p(\theta, \gamma)$

Latent GP $g(\omega) \mid \theta \sim GP\left(\mu(\omega;\theta), k_g(\omega,\omega';\theta)\right)$

Spectral Density $S(\omega) = \exp\{g(\omega)\}\$

Data GP $f(x) \mid S(\omega), \gamma \sim GP(\gamma_0, k(\tau; S(\omega)) + \gamma_1 \delta_{\tau=0})$



LATENT MODEL

Mean of latent GP is log of RBF spectral density

$$\mu(\omega; \theta) = \theta_0 - \frac{\omega^2}{2\tilde{\theta_1}^2}$$

Covariance is Matérn with $\nu = 1.5$

$$k_{g}(\omega,\omega';\theta) = \frac{2^{1-\nu}}{\Gamma(\nu)} \left(\sqrt{2\nu} \frac{|\omega - \omega'|}{\tilde{\theta}_{2}} \right) K_{\nu} \left(\sqrt{2\nu} \frac{|\omega - \omega'|}{\tilde{\theta}_{2}} \right) + \tilde{\theta}_{3} \delta_{\tau=0}$$

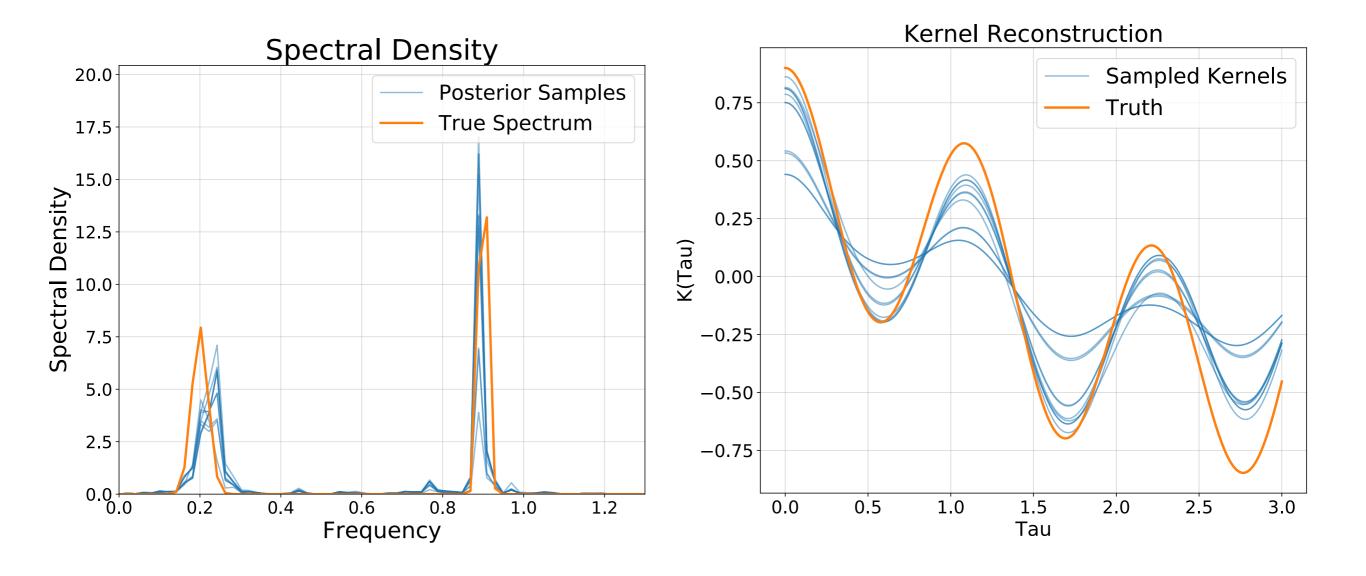
INFERENCE

- lacktriangle Need to update the hyper parameters ϕ and the latent GP $g(\omega)$
- Initialize $g(\omega)$ to the log-periodogram of the data
- Alternate:
 - Fix $g(\omega)$ and use Adam to update ϕ
 - Fix ϕ and use elliptical slice sampling to draw samples of $g(\omega)$

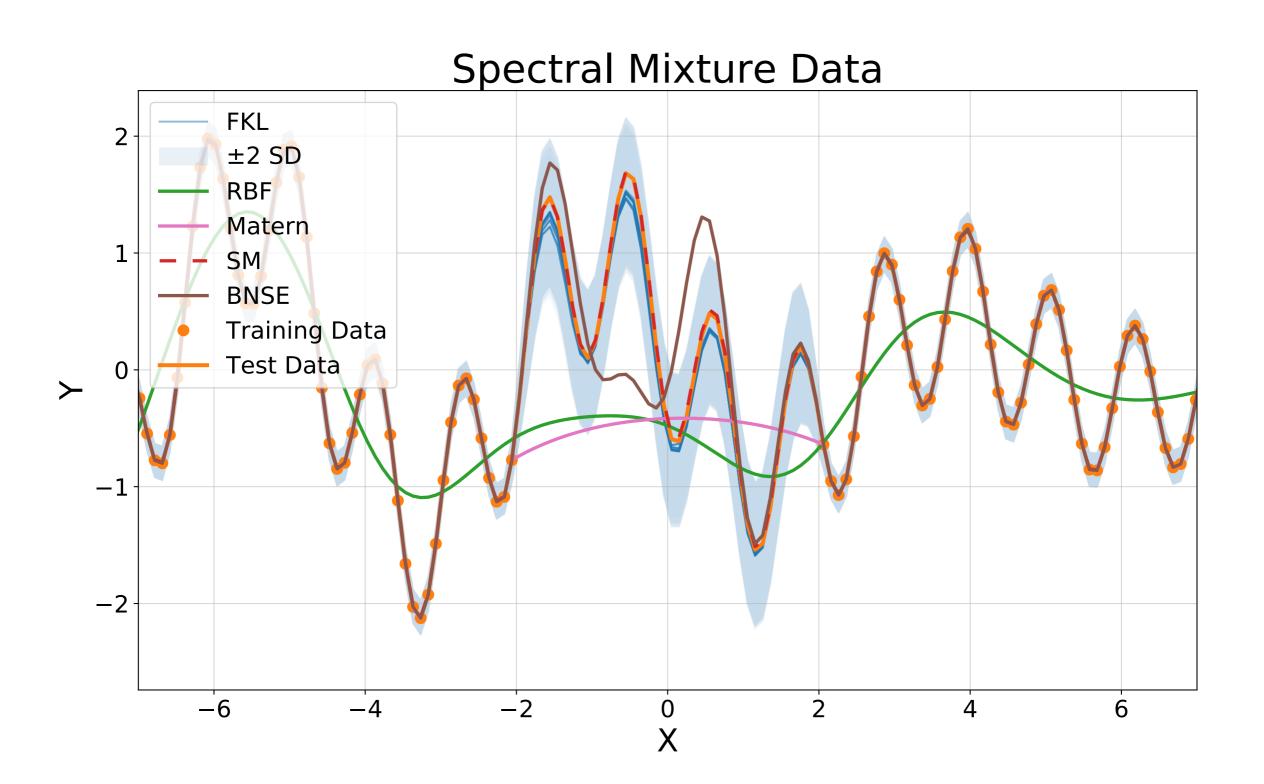
- Introduction
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DATA FROM A SPECTRAL MIXTURE KERNEL

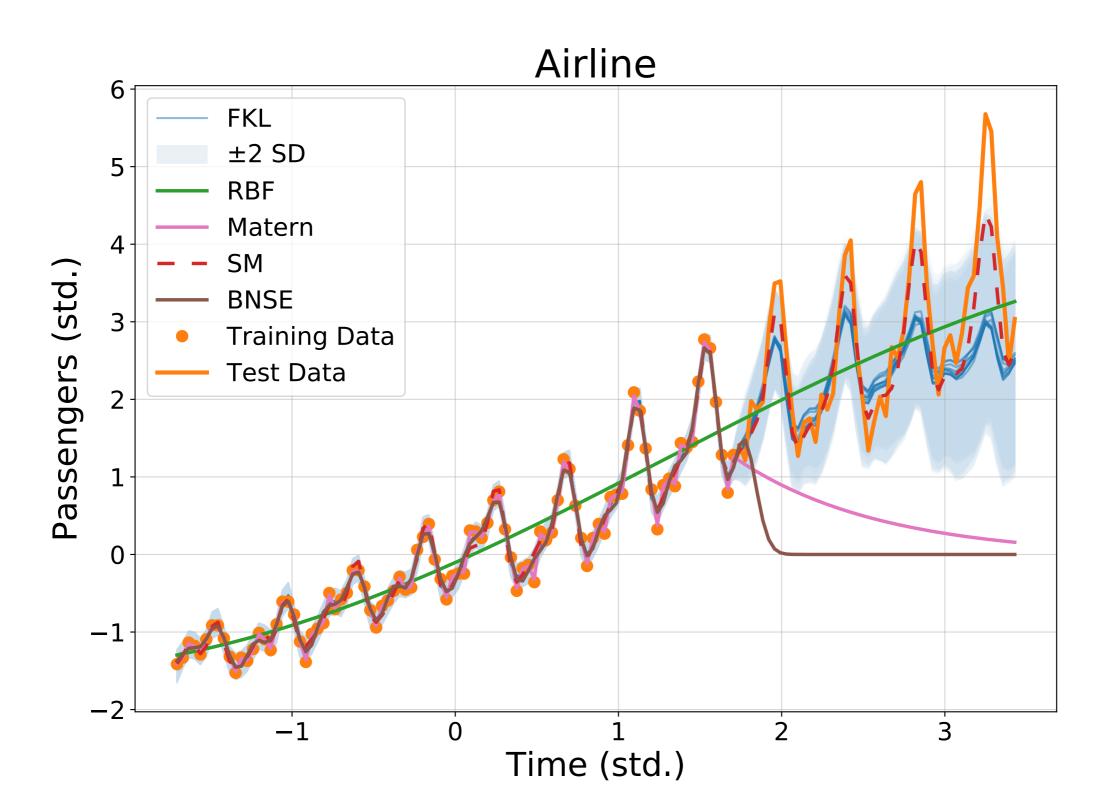
Generative kernel has mixture of Gaussians as spectral density



DATA FROM A SPECTRAL MIXTURE KERNEL



AIRLINE PASSENGER DATA



- Introduction
- Experimental Results
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 - Precipitation data

MULTIPLE TIME SERIES

- Can 'link' multiple time series by sharing the latent GP across outputs
- Let $g^t(\omega)$ denote the t^{th} realization of the latent GP and $f_t(x)$ be the GP over the t^{th} time-series

Hyper-prior
$$p(\phi) = p(\theta, \gamma)$$
 Latent GP
$$g(\omega) \mid \theta \sim GP\left(\mu(\omega; \theta), k_g(\omega, \omega'; \theta)\right)$$

$$t^{th} \text{ Spectral Density } S^t(\omega) = \exp\{g^t(\omega)\}$$
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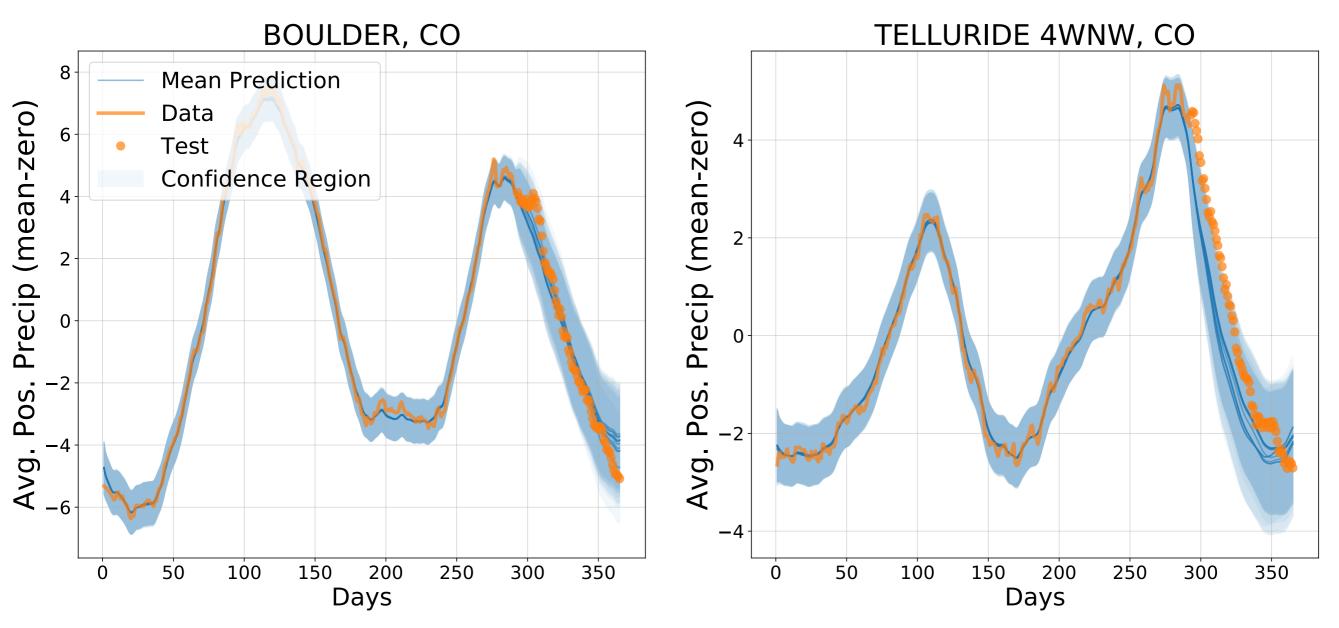
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- Test this on data from USHCN, daily precipitation values from continental US
 - Inductive bias: yearly precipitation for climatologically similar regions should have similar covariance, similar spectral densities

PRECIPITATION DATA

Ran on two climatologically similar locations

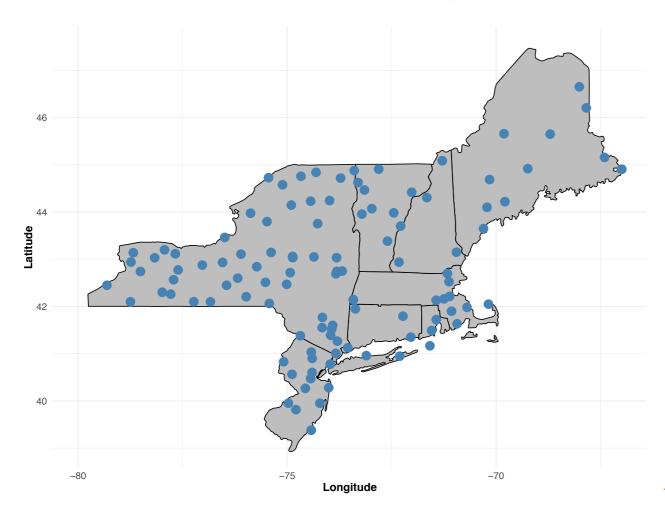


PRECIPITATION DATA

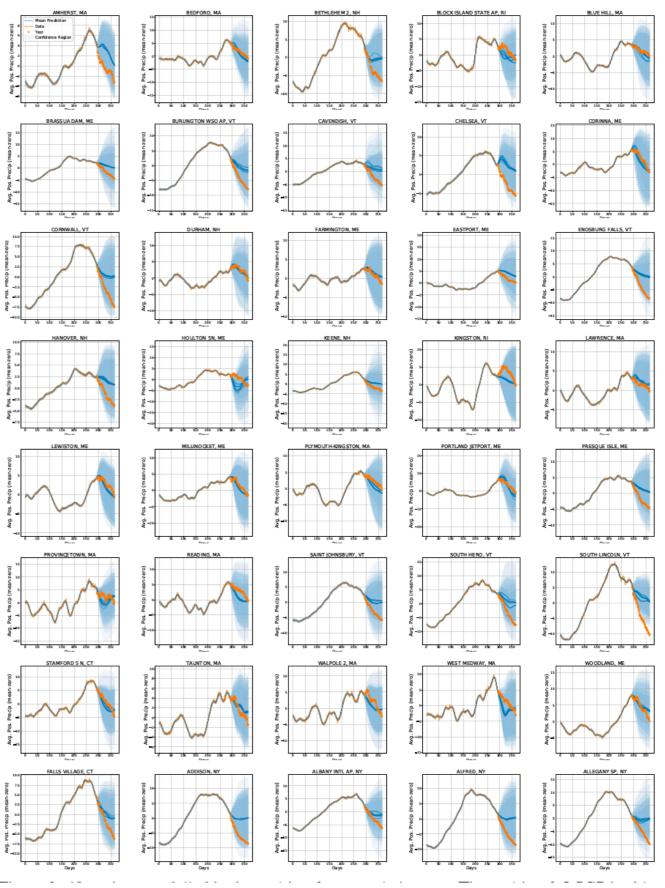
Used 108 locations across the Northeast USA

Each station, n = 300

Total: 300 * 108 = 32,400 data points







Here's 48 of them...

CONCLUSION

- FKL: Nonparametric, function-space view of kernel learning
- Can express *any* stationary kernel with uncertainty representation
- GPyTorch Code: https://github.com/wjmaddox/spectralgp



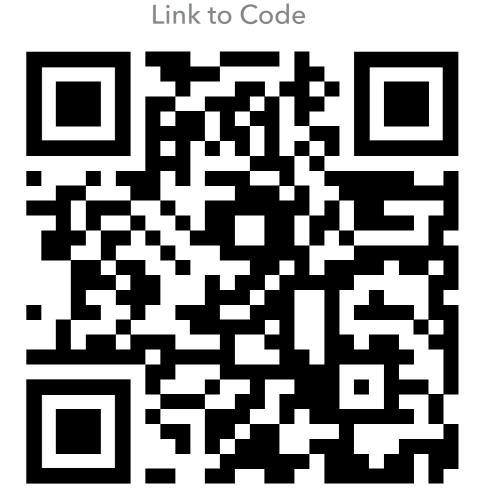


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QUESTIONS?

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REFERENCES

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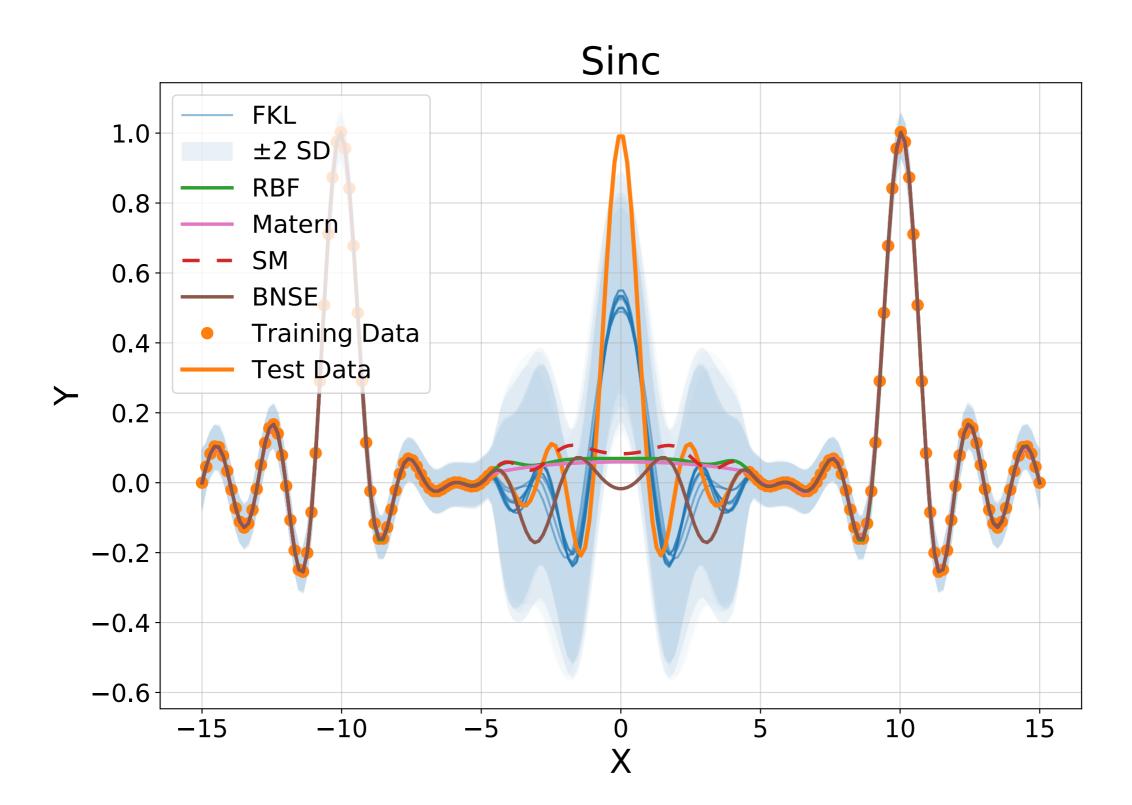
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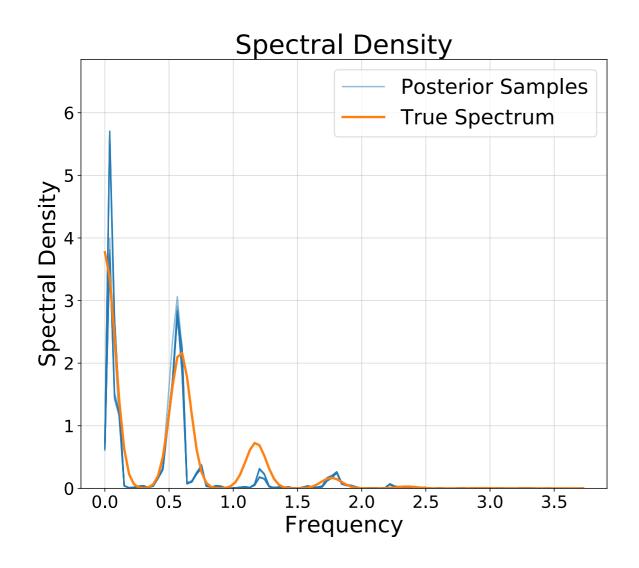
SINC DATA

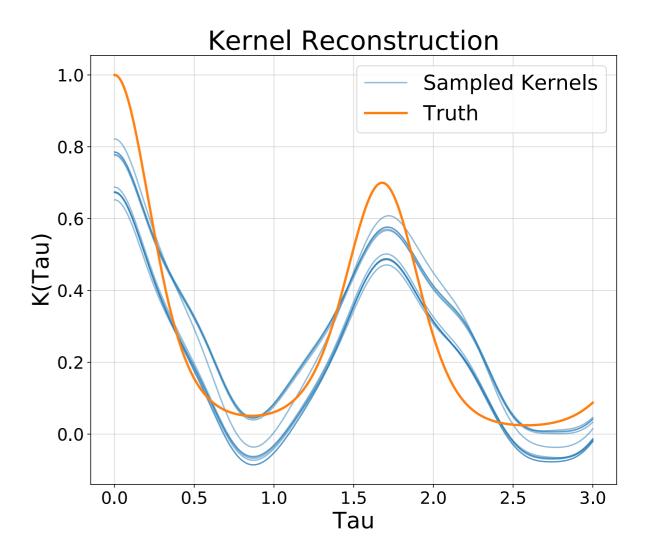
 $\operatorname{sinc}(x) = \sin(\pi x)/(\pi x)$



QUASI-PERIODIC DATA

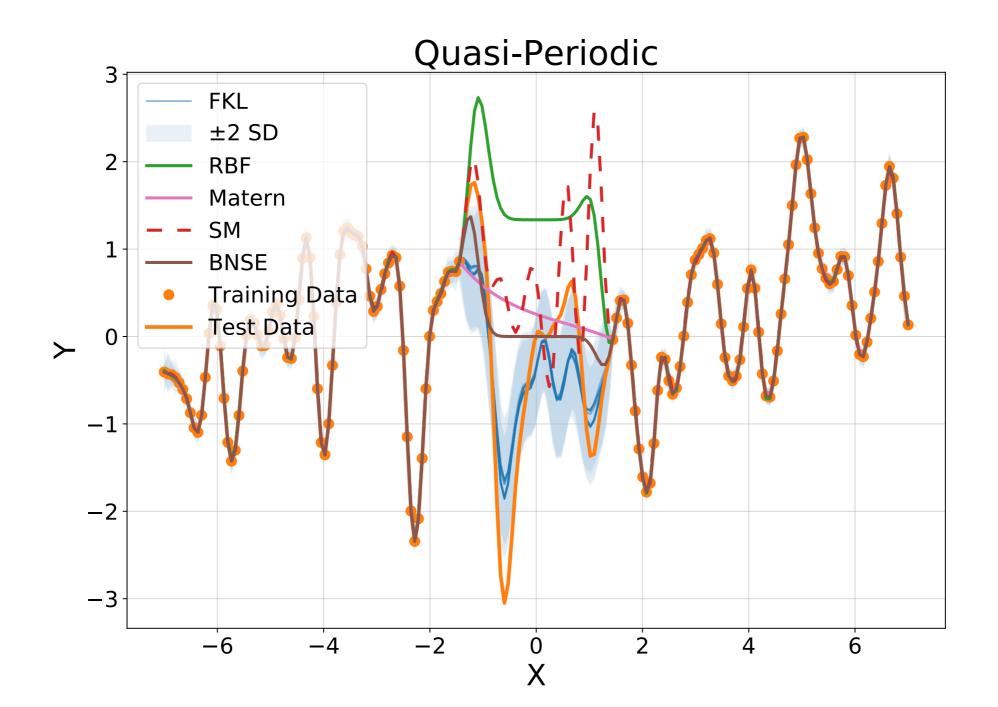
Generative kernel is product of RBF and periodic kernels





QUASI-PERIODIC DATA

Generative kernel is product of RBF and periodic kernels



ELLIPTICAL SLICE SAMPLING (MURRAY, ADAMS, MACKAY, 2010)

Sample zero mean Gaussians

Re-parameterize for non-zero mean

Input: current state \mathbf{f} , a routine that samples from $\mathcal{N}(0,\Sigma)$, log-likelihood function $\log L$.

Output: a new state \mathbf{f}' . When \mathbf{f} is drawn from $p^*(\mathbf{f}) \propto \mathcal{N}(\mathbf{f}; 0, \Sigma) L(\mathbf{f})$, the marginal distribution of \mathbf{f}' is also p^* .

- 1. Choose ellipse: $\nu \sim \mathcal{N}(0, \Sigma)$
- 2. Log-likelihood threshold:

$$u \sim \text{Uniform}[0, 1]$$

 $\log y \leftarrow \log L(\mathbf{f}) + \log u$

3. Draw an initial proposal, also defining a bracket:

$$\theta \sim \text{Uniform}[0, 2\pi]$$
$$[\theta_{\min}, \theta_{\max}] \leftarrow [\theta - 2\pi, \theta]$$

- 4. $\mathbf{f}' \leftarrow \mathbf{f} \cos \theta + \boldsymbol{\nu} \sin \theta$
- 5. if $\log L(\mathbf{f}') > \log y$ then:
- 6. Accept: **return f**'
- 7. **else:**

Shrink the bracket and try a new point:

- 8. if $\theta < 0$ then: $\theta_{\min} \leftarrow \theta$ else: $\theta_{\max} \leftarrow \theta$
- 9. $\theta \sim \text{Uniform}[\theta_{\min}, \theta_{\max}]$
- 10. **GoTo** 4.

Figure 2: The elliptical slice sampling algorithm.

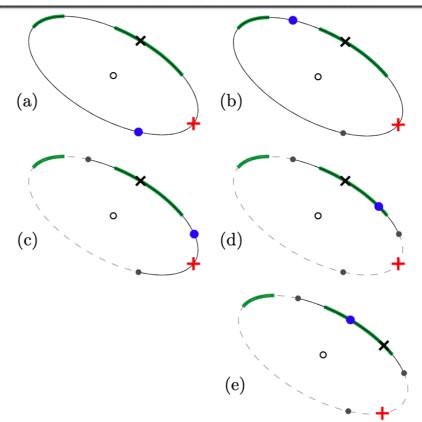


Figure 3: (a) The algorithm receives $\mathbf{f}=\mathbf{X}$ as input. Step 1 draws auxiliary variate $\boldsymbol{\nu}=\boldsymbol{+}$, defining an ellipse centred at the origin (o). Step 2: a likelihood threshold defines the 'slice' (—). Step 3: an initial proposal • is drawn, in this case not on the slice. (b) The first proposal defined both edges of the $[\theta_{\min}, \theta_{\max}]$ bracket; the second proposal (•) is also drawn from the whole range. (c) One edge of the bracket (—) is moved to the last rejected point such that \mathbf{X} is still included. Proposals are made with this shrinking rule until one lands on the slice. (d) The proposal here (•) is on the slice and is returned as \mathbf{f}' . (e) Shows the reverse configuration discussed in Section 2.3: \mathbf{X} is the input \mathbf{f}' , which with auxiliary $\mathbf{\nu}'=\mathbf{+}$ defines the same ellipse. The brackets and first three proposals (•) are the same. The final proposal (•) is accepted, a move back to \mathbf{f} .